

# Basic Math Review for CS4830

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## Definition of a set

A set is a collection of distinct objects, considered as an object in its own right. For example, the numbers 2, 4, and 6 are distinct objects when considered separately, but when they are considered collectively they form a single set of size three, written  $\{2, 4, 6\}$ . Sets are one of the most fundamental concepts in mathematics.

## Have to know symbols

- $\in$ : set membership. Example:  $x \in \mathbb{R}$  is read  $x$  belongs to the set  $\mathbb{R}$ .
- $\cup$ : union. Example:  $X = A \cup B$  is read:  $X$  is the result of  $A$  union  $B$ , and contains **all** elements of  $A$  and  $B$ .
- $\cap$ : intersection. Example  $X = A \cap B$  is read  $X$  is the result of  $A$  intersect  $B$ , and contains elements that are in **BOTH**  $A$  and in  $B$

# Number sets

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## Rationals

- Rational numbers:  $\mathbb{Q}$
- Examples:  $\frac{1}{2}$ ,  $\frac{2}{3}$ ,  $-\frac{10}{7}$ ,  $\frac{1}{3}$
- More generally, rational numbers are ratios of two whole numbers:  $\frac{a}{b}$ , where  $a, b \in \mathbb{Z}$  subject to  $b \neq 0$

# Number sets contd.

## Irrationals

$$1.5 = \frac{3}{2} \begin{array}{l} \text{Ratio} \\ \text{Rational} \end{array}$$

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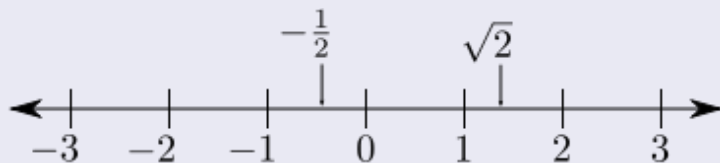
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## Reals

- Real numbers:  $\mathbb{R}$



## Imaginary numbers

- Imaginary numbers:  $\mathbb{I}$
- They are numbers that, when squared, result in a negative number
- Example:  $\sqrt{-9} = 3i$ , because  $(3i)^2 = -9$ , here  $i^2 = -1$

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## What about $i$

Is  $i$  also an algebraic number?

## Complex

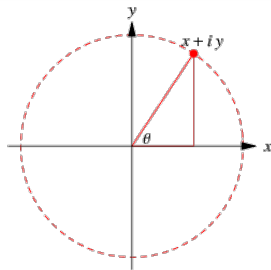
- Complex numbers:  $\mathbb{C}$
- They are a combination of a real and an imaginary number
- Examples  $10 - 2i, 2 + 3i$
- More generally, they have the form  $x + iy$ , where  $x, y \in \mathbb{R}$



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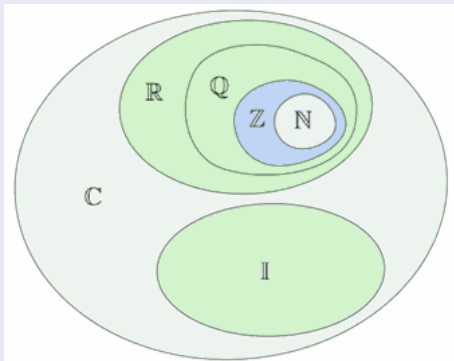
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# Operations on numbers

## Venn diagram of number sets



## Common operations

- Addition:  $2 + 3 = 5$
- Subtraction  $2 - 3 = -1$
- Multiplication  $2 * 3 = 6$
- Division  $\frac{2}{3} = 0.(6)$
- Exponentiation  $2^3 = 8$

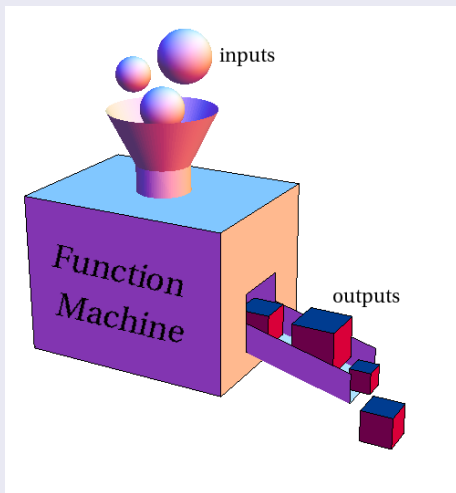
## Variable may refer to:

- In research: a logical set of attributes
- In mathematics: a **symbol** that represents a quantity in a mathematical expression
- In **computer science**: a **symbolic name** associated with a value and whose associated value may be changed

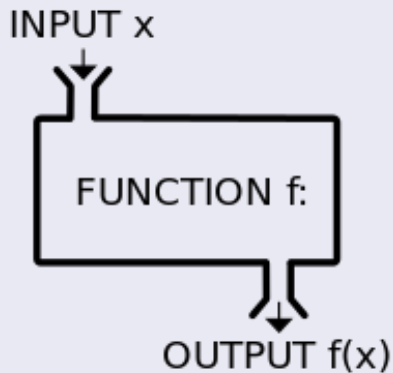
We shall use all 3 flavors in this course.

What is a function?

## Intuition



## Intuition useful for computer scientists

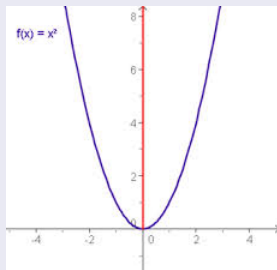


# Functions

## Informal definition

Think of a function as a “process” that takes input  $x$  and produces output  $f(x)$ . For example, the function  $f(x) = x^2$ , takes an input  $x$  (a number) and “processes” it by squaring it.

## Plotting a function with a single number as input





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- The output  $Y$ , is also referred to as the **dependent variable** or **response variable**, **regressand**, **measured variable**, **outcome variable**, **output variable**, etc.

## Composition

The idea is to “process” the input through one function, then use the result of that function as the input to the second. This results in a different function.

- Notation: given two functions  $f$  and  $g$ , the composition of  $g$  and  $f$  is written as  $(g \circ f) = g(f(x))$ .
- Example: if  $f(x) = 2x + 3$ , and  $g(x) = x^2$ , then  $(g \circ f) = g(f(x)) = g(2x + 3) = (2x + 3)^2 = 4x^2 + 12x + 9$ .
- $(f \circ g) \neq (g \circ f)$ .

## Differentiation/Integration

Rates of change and areas under the curve.

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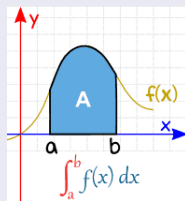
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- Indefinite integral of a function  $f$  is written as  $\int f(x)dx$
- Definite integral of a function  $f$  over an interval  $[a, b]$  is written as  $\int_a^b f(x)dx$

# Operations on functions

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In Calculus courses you were probably taught **analytic** solutions to differentiation and integration problems. In the real-world, you will most likely deal with numerical differentiation and integration. More on that later in the course.

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# Vector and Matrix Algebra

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## Vector elements

The position of the scalar in the ordered set is referred to as the **index**. In the example above, the index of the element 2 is 1, since it is the first element in the set. The index of 3 is 2, since it is the second element.

## Vector dimensionality

- The number of elements a vector has is referred to as its **dimensionality**. For example, the vector  $X = [x_1, x_2, x_3]$  has dimensionality 3, and if  $x_1, x_2, x_3 \in \mathbb{R}$ , then it is denoted as  $X \in \mathbb{R}^3$ .
- There can be any number dimensional vectors. For example 6-dimensional vectors  $\in \mathbb{R}^6$ .

# More about vectors

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## Vector magnitude

- A vector's magnitude is the distance (or L2-norm) from the origin of the space it "lives" in and a point. The magnitude is **computed** using the Pythagorean theorem (more accurately, a generalization of that known as Euclidian distance) using the following formula and notation:

$$|X| = \sqrt{\sum_{i=1}^n x_i^2} \quad (1)$$



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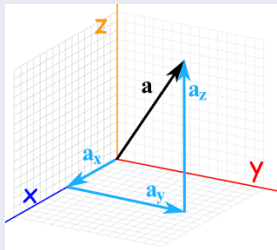
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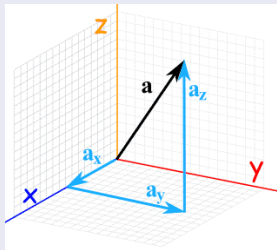


When the tail and the head are points on 2D plane, how can we compute magnitude?

# 3D visualization



# 3D visualization



## In-class exercise

If  $\mathbf{a} = [1, 2, 3]$ , what is  $|\mathbf{a}|$ ?

## Definition

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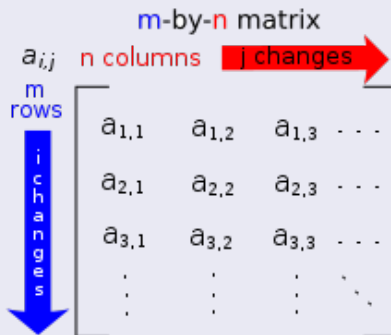
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## Example

$$A = \begin{bmatrix} 4.86 & 0 & 0 & 0 & 0 & -2.60 & 0 & 0 & 0 & 0 \\ 0 & 5.13 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 5.03 & 1.29 & 1.41 & 0 & 0 & 2.05 & 0 & 0.04 \\ 0 & 0 & 1.29 & 0.99 & 0 & 0 & 0 & 0 & 0 & -0.79 \\ 0 & 0 & 1.41 & 0 & 5.45 & 0 & 0 & 0 & 0 & 0 \\ -2.60 & 0 & 0 & 0 & 0 & 2.60 & 0.17 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0.17 & 1.16 & 0 & 0 & 0 \\ 0 & 0 & 2.05 & 0 & 0 & 0 & 0 & 1.64 & 0 & 0.21 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 2.48 & 0 \\ 0 & 0 & 0.04 & -0.79 & 0 & 0 & 0 & 0.21 & 0 & 4.21 \end{bmatrix}$$



## Structure in the 2D case



## Rows and Columns

- One can also think of a matrix as a collection of rows **or** a collection of columns.
- Or as a collection of **row vectors** or **column vectors**

## Row/Column vectors

$$X = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$$

$$Y = [1 \quad 2 \quad 3]$$

- $X$  has dimensionality  $3 \times 1$ , and is called a column vector
- $Y$  has dimensionality  $1 \times 3$ , and is called a row vector

## Collection of column vectors

Given  $X_1 = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$  and  $X_2 = \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix}$ , we can form a matrix  $Z$  using  $X_1$  and  $X_2$ :

$$Z = [X_1 \quad X_2] = \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix}$$

## Collection of row vectors

Given  $X_1 = [1 \ 2 \ 3]$  and  $X_2 = [4 \ 5 \ 6]$ , we can form a matrix  $Z$  using  $X_1$  and  $X_2$ :

$$Z = \begin{bmatrix} X_1 \\ X_2 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}$$

Say,  $Z = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}$ . The matrix is 2 rows by 3 columns (2x3).

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$$Z = \begin{bmatrix} Z_{1,1} & Z_{1,2} & Z_{1,3} \\ Z_{2,1} & Z_{2,2} & Z_{2,3} \end{bmatrix}$$

each  $Z_{i,j}$  where  $i \in \{\text{possible rows}\}$  and  $j \in \{\text{possible columns}\}$ , where possible rows for  $Z$  is the set  $\{1, 2\}$  and the possible columns for  $Z$  is the set  $\{1, 2, 3\}$ .

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“Where” is 5?

Second row, second column:  $Z_{2,2}$

## Addition and subtraction

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If  $A$  is  $r$  by  $c$ , and  $B$  is  $r$  by  $c$ , then for  $C = A + B$ ,  $C_{ij} = A_{ij} + B_{ij}$ , similarly if  $C = A - B$ ,  $C_{ij} = A_{ij} - B_{ij}$ .

## Multiplication

Matrix multiplication summarizes a set of multiplications and additions.

- Multiplication of matrix by scalar: simply multiply each element of the matrix by the scalar.

Example:  $a = 2$  and  $X = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}$ , then  $Ax$  or  $xA$  is a matrix formed as

follows: 
$$\begin{bmatrix} 2 * 1 & 2 * 2 & 2 * 3 \\ 2 * 4 & 2 * 5 & 2 * 6 \end{bmatrix} = \begin{bmatrix} 2 & 4 & 6 \\ 8 & 10 & 12 \end{bmatrix}$$

## Multiplication

Multiplication of two matrices:

- The two matrices must be **conformable**, that is if  $A$  is  $r_1$  by  $c_1$  and  $B$  is  $r_2$  by  $c_2$ , then  $C = A \times B$  is defined when  $c_1 = r_2$  and  $C$  is of size  $r_1$  by  $c_2$ .
- $C_{ij}$  is found by multiplying each element of row  $i$  of  $A$  with each element of column  $j$  of  $B$  and adding up the multiplied pairs of real numbers.

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- $(cA)^T = cA^T$

## On vectors

Transpose of a row vector results in a column vector. Transpose of a column vector results in a row vector.

# Inner and outer products of vectors

Given two vectors with the same number of elements, e.g.:  $a$  and  $b$  both  $r$  by 1, we can define the inner and outer products as follows:

## Inner product

$$a^T b = \sum_{i=1}^r a_i b_i \quad (2)$$

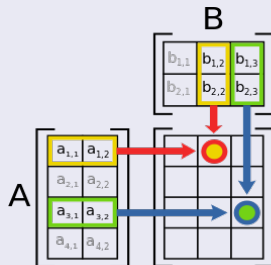
The inner product of a vector  $v$  with itself  $v^T v$  is equal to the sums of squares of its elements, so has the property  $v^T v \geq 0$ .

## Outer product

The outer product results in a matrix, of size  $r$  by  $r$ . If  $O = ab^T$  is the outer product matrix, then  $O_{ij} = a_i b_j$ .

# Operations on vectors and matrices

## Multiplication



- Elements in the resulting matrix  $M = A * B$ ,  $M_{ij} = \text{dot}(A[i, *], B[* , j])$ , where  $*$  indicates all possible rows/columns, and  $\text{dot}$  is the inner product (results in a scalar).
- $A[i, *]$  is a row vector,  $B[* , j]$  is a column vector.

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- Symmetric matrices: square matrices that have the same numbers above and below the main diagonal, i.e., a matrix  $A$  is symmetric if and only if  $A_{ij} = A_{ji}$ .

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- Square matrices: have the same number of rows and columns
- Diagonal matrices: square matrices that have all except the elements on the main diagonal equal to 0
- Symmetric matrices: square matrices that have the same numbers above and below the main diagonal, i.e., a matrix  $A$  is symmetric if and only if  $A_{ij} = A_{ji}$ .
- Identity matrix: diagonal matrix with all 1s on the main diagonal



# Trace and determinants of square matrices

## Trace

The trace of a square matrix is the sum of elements in its main diagonal. For a matrix  $A$  of size  $r \times r$ , its trace, denoted as  $Tr(A)$  is:

$$Tr(A) = \sum_{i=1}^r A_{ii}$$

Important property:  $tr(A) = \sum_i \lambda_i$ , where  $\lambda_i$  are the eigenvalues of matrix  $A$ .

## Determinant

The determinant of a square matrix is a difficult calculation, but serves important purposes in optimization problems. Often, the sign is more important than its exact value. An important property is:  $det(A) = \prod_i \lambda_i$